

Mechanical Energy Absorbers and Aluminum Honeycomb

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In this paper general equations for a replaceable element energy absorber are presented. For long stroke application (1 m or more) a metal cutting energy absorber is preferred. For shorter stroke applications crushing of aluminum honeycomb material is suggested. To evaluate the usefulness of aluminum honeycomb, as an energy absorber, a drop test apparatus was designed and built. Results suggest two effects, a geometry ("size") effect and an impact velocity effect, cause the dynamic crush strength of the honeycomb to be different than static crush strength values. Experimentally the net effect causes less than 20 percent difference between static and dynamic crush strengths at extrapolated impact velocities of 50–100 m/s (164–328 ft/s).

Introduction

Shock protection involves the dissipation of kinetic energy while maintaining a tolerable level of deceleration. This protection may be required to prevent failure of mechanical or electrical components or for human operators in moving vehicles.

For applications where impact is expected to occur infrequently a replaceable element energy absorber (the equivalent of an electrical fuse) may be considered. The remainder of this paper will deal only with replaceable element energy absorbers.

Replaceable Element Energy Absorbers

To better formulate the requirements of a replaceable element energy absorber material consider the drop test shown schematically in Fig. 1. For this example a weight, w , initially at rest, drops from a height, h , onto the energy absorber. The velocity at impact is:

$$V_0 = \sqrt{2gh} \quad (1)$$

and during the interval after impact the equation of motion for the weight (w) is given below.

$$F = \frac{w}{g} (g - \ddot{x}) \quad (2)$$

In addition, the work done on the mass (by the absorber) must equal the change in potential energy of the mass between the start of the process and the finish.

$$\Delta PE = w(h + l_s) \quad (3)$$

$$\text{Work} = \int_0^{l_s} F dx \quad (4)$$

Note that F is the stopping force applied to the mass by the absorber.

For the ideal absorber an optimal choice for F is to have it constant over the stroke length (l_s). This choice will result in a minimum stroke length. Assuming F is constant, equations (3) and (4) can be combined and l_s solved for.

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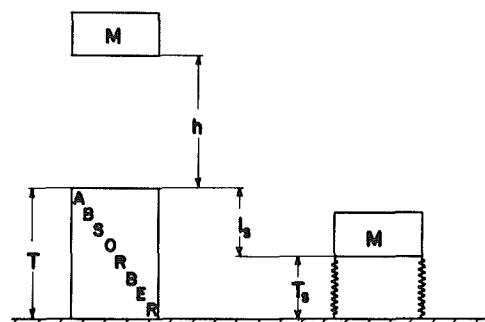


Fig. 1 Schematic of drop test

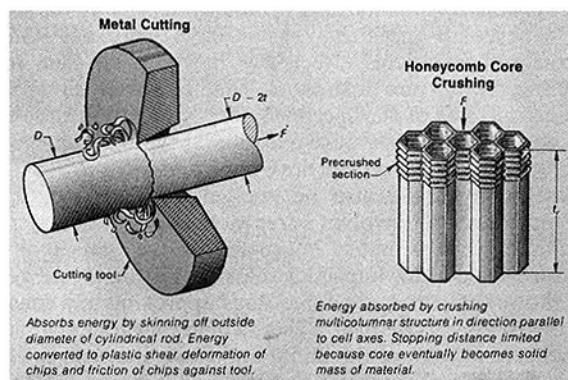


Fig. 2 Two processes for expendable element energy absorbers (from [1])

$$l_s (\text{constant force}) = \frac{h}{\frac{F}{w} - 1} \quad (5)$$

Kirk and Overway [1] have surveyed potential materials and processes which could provide a constant retarding force (F) independent of velocity and displacement. The authors concluded that the two most favorable processes are metal cutting and crushing of aluminum honeycomb core material. These are shown schematically in Fig. 2. The authors further

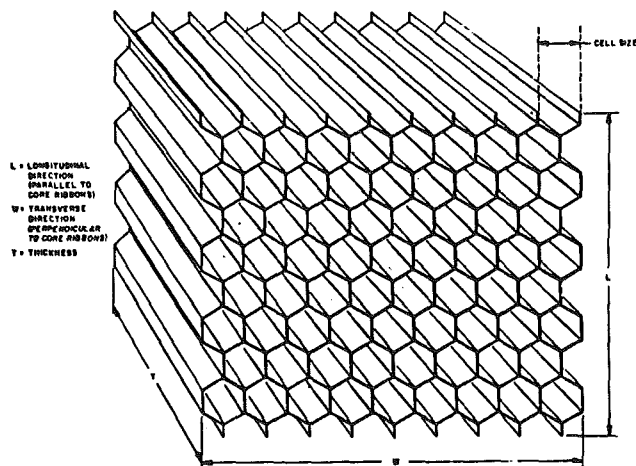


Fig. 3 Reference dimensions for honeycomb (from [10])

suggest that for long stroke applications (l_s greater than about 1 m) metal cutting would be preferred.

Metal cutting for energy absorption has been discussed by Shaw [2], Pleck et al. [3] and Kirk and Gay [4]. Kirk [5] has also reported on a metal cutting apparatus which has successfully been used to stop subway cars at the end of line runs.

Crushing of aluminum honeycomb was briefly discussed in a survey article by Coppia [6] on "New Ways to Soften Shock". Although there was not much space to provide details the results presented suggest that the crushing force (i. e. stopping force) increases very little (≈ 2 percent) as impact velocity increases from very slow (near 0) to 30 m/s (100 ft/s). Other researchers such as Conn [7] and Lewallen and Ripperger [8] have used air guns to propel projectiles into an aluminum honeycomb material; however, their work does not appear to have been widely published in the open literature. Their data, in general, suggest that the crushing force does not depend on impact velocity over the range very slow to greater than 30 m/s. In tests by both Conn and Lewallen and Ripperger the honeycomb cross section was the same for all tests. Additional work by Ripperger and Reifel [9] has indicated that the honeycomb retarding force may depend on the size of the honeycomb specimen. The authors were not able to precisely quantify this effect, but they suggest that larger retarding forces are associated with larger crush area to perimeter ratios of the specimen. This conclusion, however, was based upon testing of two dissimilar types of honeycomb having different test geometries (round and square).

Finally, it should also be pointed out that the typical dynamic crush test involves a free moving mass impacting the aluminum honeycomb. Photographic or accelerometer measurements of the impacting mass (Cohn and Ripperger, et al.) shows that the crush force stays approximately constant as the mass decelerates. This would suggest that it is reasonable to look at the initial and final dimensions of the honeycomb in order to evaluate energy absorber behavior.

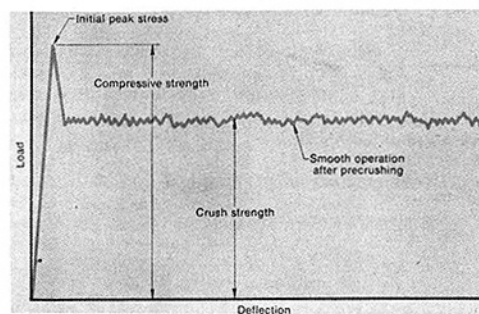


Fig. 4 Aluminum honeycomb core crushing behavior (from [1])

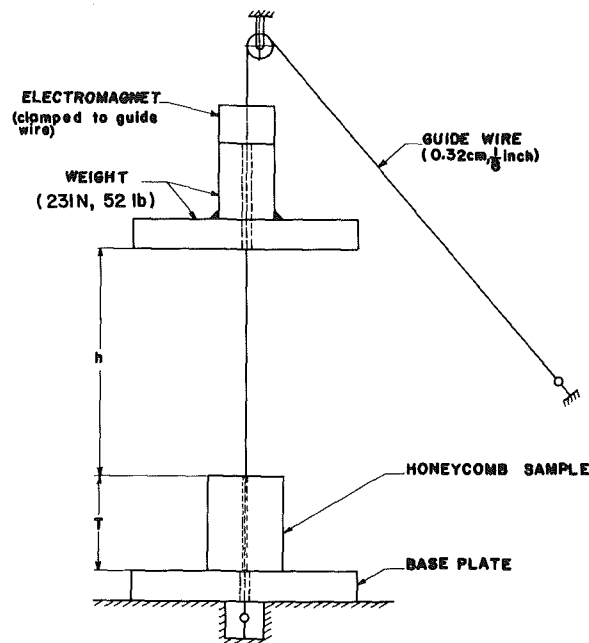


Fig. 5 Drop test apparatus

Honeycomb Parameters

Honeycomb material refers to a geometric arrangement of thin sheets (e. g. aluminum) bonded together to form cells of uniform shapes, usually hexagonal. The cores are made by either assembling corrugated ribbons or by strip bonding flat ribbons and then expanding the core cells to the proper shape. Reference areas for honeycomb cores are shown in Fig. 3.

The parameters which are controlled by the manufacturer of the honeycomb, and which determine the mechanical behavior, are foil material, foil thickness, and cell size (across flats). The two honeycomb manufacturers follow the format of reference [10] in describing honeycomb behavior in their technical literature [11, 12].

If a hexagonal core honeycomb is slowly compressed (at

Nomenclature

A = honeycomb crush area, cm^2	\bar{l}_s = average crush length, m	V_0 = impact velocity, m/s
f_{cr} = static crush strength, Pa	L = honeycomb longitudinal direction, cm	w = impact weight, N
f_{crd} = dynamic crush strength, Pa	P = honeycomb perimeter, cm	W = honeycomb transverse direction, cm (perpendicular to core ribbons)
F = retarding force, N	P.E. = potential energy, Nm	\ddot{x} = impact weight acceleration, m/s^2
g = acceleration of gravity, m/s^2	T = honeycomb thickness, cm	
h = drop height, m	\bar{T}_s = average crushed honeycomb thickness, cm	
l_s = crush (or stroke) length, m		

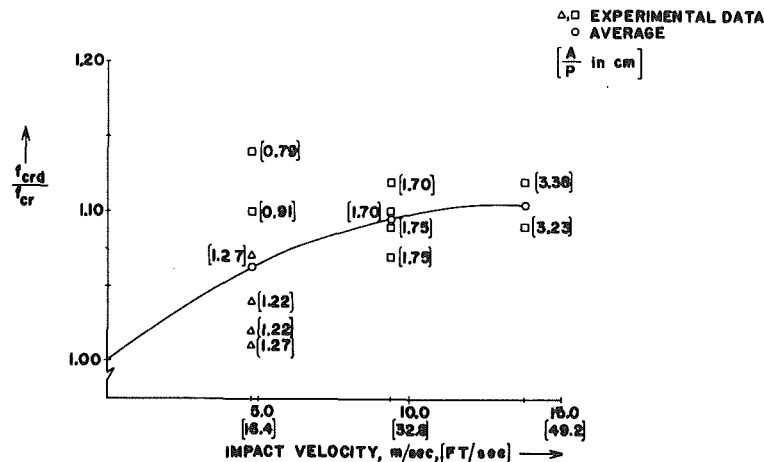


Fig. 8 Dynamic crush strength versus impact velocity; type II honeycomb, $f_{cr} = 938 \text{ kPa (138 psi)}$

sample geometry effect ("size effect") which causes a variation in f_{crd} . The larger the honeycomb crush area compared to the perimeter (larger A/P ratios) the smaller the value of f_{crd} . It would thus appear that the size effect ratio (A/P) tends to lower f_{crd} . Because of the limited testing at other impact velocities it can not be stated at this time whether the size effect is less important at larger A/P ratios or higher impact velocities. Current work is underway to understand more about the cause of the size effect.

In addition to the size effect the results shown in Figs. 7 and 8 suggest that f_{crd} increases with increasing impact velocity. In both figures the size effect ratios (A/P) are larger at the higher impact velocity tests. Since the size effect ratio appears to lower f_{crd} these results suggest a trend of increasing f_{crd} with impact velocity. A higher f_{crd} at larger impact velocities is consistent with the explanation that the yield strength of the aluminum foil material is greater at higher strain rates (i. e. at higher impact velocities).

The combination of the size effect ratio (A/P) decreasing f_{crd} and the velocity effect increasing f_{crd} , hold overall f_{crd} variations to less than 20 percent at impact velocities up to 15.0 m/s (49 ft/s). Since the average f_{crd}/f_{cr} curve flattens out considerably at impact velocities above 10 m/s (33 ft/s) it would appear that this aluminum honeycomb material would behave predictably at much higher impact velocities. The material would thus make an excellent energy absorber for a wide range of impact velocities.

Conclusions

A drop test apparatus for evaluating the crush behavior of aluminum honeycomb, at various impact velocities, has been described. Results of drop testing has identified two effects which influence the dynamic crush strength of the aluminum honeycomb.

- 1 The first effect is termed a size effect and depends on the A/P ratio of a sample. As the A/P ratio increases, f_{crd} decreases.
- 2 The second effect is termed a velocity effect and depends on impact velocity. As impact velocity increases, f_{crd} increases.

Experimentally, for two different honeycomb samples, the combination of these two effects causes less than a 20 percent increase in dynamic crush strength (f_{crd}) up to an impact

velocity of 15.0 m/s (and extrapolated to possibly 50 - 100 m/s).

The results presented in this paper suggest that aluminum honeycomb is an excellent energy absorber for a wide range of impact velocity applications. It would appear that the static crush strength (f_{cr}) is a reasonable predictor of dynamic crush behavior (when used with an appropriate factor of safety).

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